Boundary Yang-Baxter equation in the RSOS/SOS representation

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Abstract

We construct and solve the boundary Yang-Baxter equation in the RSOS/SOS representation. We find two classes of trigonometric solutions; diagonal and non-diagonal. As a lattice model, these two classes of solutions correspond to RSOS/SOS models with fixed and free boundary spins respectively. Applied to (1+1)-dimenional quantum field theory, these solutions give the boundary scattering amplitudes of the particles. For the diagonal solution, we propose an algebraic Bethe ansatz method to diagonalize the SOS-type transfer matrix with boundary and obtain the Bethe ansatz equations.

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1 Introduction

In the study of the two-dimensional integrable models of quantum field theories and statistical models, the Yang-Baxter equation (YBE) plays essential roles in establishing the integrability and solving the models. In the field theories, the YBE provides a consistency condition for the two-body scattering amplitudes (S-matrices) in the multi-particle scattering processes since the scattering is factorizable. With unitarity and crossing symmetry, the YBE can determine the S-matrix completely, although not uniquely due to the CDD factor which is any function of the rapidity satisfying the unitarity and crossing symmetry conditions. This CDD factor is usually neglected under the the minimality assumption. In the statistical models, if the Boltzmann weights satisfy the YBE, row-to-row transfer matrices with different values of the spectral parameter commute each other so that the models are integrable.

Recently there has been a lot of efforts in extending these approaches to models with boundaries. The main motivation is that these models can be applied to 3D spherically symmetric physical systems where s-wave element becomes dominant. One-channel Kondo problem, monopole-catalyzed proton decay are frequently cited examples. Also one can generalize the conventional periodic boundary condition of the statistical models to other types like the fixed and free conditions.

The existence of the boundary adds new quantities like boundary scattering amplitudes and boundary Boltzmann weights, and one needs to extend the YBE to include these objects. The boundary Yang-Baxter equation (BYBE) (also known as the reflection equation) [1] plays the role of the YBE for the integrable statistical models [2, 3] and quantum field theories [4] in the presence of a boundary; it is the necessary condition for the integrability of these models. The equation takes the form

$$R_1(u)S_{12}(u^{'}+u)R_2(u^{'})S_{12}(u^{'}-u) = S_{12}(u^{'}-u)S_2(u^{'})S_{12}(u^{'}+u)R_1(u) \qquad (1.1)$$

where $R_{1(2)}$ is the boundary scattering (or reflection) matrix in the auxiliary space 1(2) and S_{12} is the solution to the YBE. In general, $R(u)$ need not be a **C**-number matrix, so the equation may be taken as the defining relation for the associative algebra generated by the symbols $R(u)$ [5]. This algebra possesses a very rich structure and has been found to be connected with braid groups [6], lattice current algebra [7], twisted Yangian [8] and so on. Taking the quantum space of $R(u)$ to be trivial, the BYBE is a quadratic matrix equation which allows the matrix $R(u)$ to be solved for given $S(u)$. To date, several solutions of the BYBE have appeared in the form of vertex representation, far less is known however for the solution in the solid on solid (SOS) or restricted solid on solid (RSOS) representation [9, 10]. Also less clear is the vertex-SOS correspondence associated with this algebra. In particular there is no reason to expect the vertex-SOS transformation for the YBE continue to hold for this algebra. Therefore finding solution

in the RSOS form may help to clarify the issue of the vertex-SOS correspondence. Moreover, the RSOS solution will reveal the special mathematical structure associated with this algebra when the deformation parameter is a root of unity.

From a physical point of view, the solutions have applications in statistical mechanics and field theory. In the context of statistical mechanics, the solutions give rise to integrable SOS/RSOS models with boundaries where the **C**-number solution of the BYBE provides the Boltzmann weights of the statistical models at the boundary. The first nontrivial case gives the tri-critical Ising model. The study of integrable statistical model with boundary will shed light on the issue of the dependence of the Casimir energy on the boundary and surface properties [11, 27]. From the field theory point of view, the solutions are relevant to the study of the restricted sine-Gordon model [16] and the perturbed (coset [12, 13]) conformal field theory (CFT) [14] with boundary. In this case, solutions to the BYBE are scattering matrices of the particles with the boundary.

In this paper we construct the BYBE in the RSOS/SOS representation. The equation is studied for the diagonal and non-diagonal cases, and the most general trigonometric solutions are found up to an overall factor. This factor is then fixed using the boundary crossing and unitarity conditions [4] (up to the usual CDD ambiguity). We then construct an integrable RSOS/SOS model using the diagonal solution and propose an algebraic Bethe ansatz method to diagonalize the transfer matrix of the SOS model.

2 Solutions to the boundary Yang-Baxter equation

2.1 Generalities

In this section we solve the BYBE for the RSOS(p) ; $p = 3, 4 \ldots$ scattering theory. The RSOS(p) scattering theory is based on a $(p-1)$ - fold degenerate vacuum structure, vacua can be associated with nodes of the $\mathcal{A}_{p-1}$ Dynkin diagram. The quasi particles in the scattering theory are kinks that interpolate neighboring vacua, they can be denoted by non-commutative symbols $K_{ab}(u)$ where $|a - b| = 1$ with $a, b = 1, \ldots, p-1$ and u is related to the the kink rapidity θ by $u = -i\theta/p$, so that the physical strip is given by $0 < \mathrm{Re}\ u < \pi/p$. In the rest of the paper, we will refer to a, b as heights or spins. Formally, scattering between two kinks can be represented by the following equation (see Fig.(1))

$$K_{da}(u)K_{ab}(u^{'}) = \sum_{c} S_{dc}^{ab}(u - u^{'})K_{dc}(u^{'})K_{cb}(u) \qquad (2.1.1)$$

where the S-matrix is given by

$$S_{dc}^{ab}(u) = \mathcal{U}(u) \left(\frac{[a][c]}{[d][b]} \right)^{-u/2\gamma} W_{dc}^{ab}(u) \tag{2.1.2}$$

and

$$W_{dc}^{ab}(u) = \left(\sin u \, \delta_{bd} \left(\frac{[a][c]}{[d][b]} \right)^{1/2} + \sin(\gamma - u)\delta_{ac} \right) \tag{2.1.3}$$
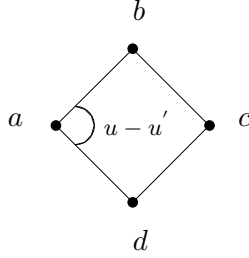
satisfies the YBE in the RSOS representation.

Figure 1:   The bulk RSOS scattering matrix $S_{dc}^{ab}(u - u')$

Here $[a]$ denotes the usual q-number given by

$$[a] = \frac{\sin(a\gamma)}{\sin\gamma} \qquad \gamma = \frac{\pi}{p}$$

and the overall factor $\mathcal{U}(u)$ is a product of Gamma functions satisfying the relations

$$\begin{aligned}
\mathcal{U}(u)\mathcal{U}(-u)\sin(\gamma - u)\sin(\gamma + u) &= 1 \\
\mathcal{U}(\gamma - u) &= \mathcal{U}(u) \,,
\end{aligned}$$

and is given by

$$\begin{aligned}
\mathcal{U}(u) &= \frac{1}{\pi}\Gamma\left(\frac{\gamma}{\pi}\right)\Gamma\left(1 - \frac{u}{\pi}\right)\Gamma\left(1 - \frac{\gamma}{\pi} + \frac{u}{\pi}\right)\prod_{l=1}^{\infty} \frac{F_l(u)F_l(\gamma - u)}{F_l(0)F_l(\gamma)}, \\
F_l(u) &= \frac{\Gamma\left(\frac{2l\gamma}{\pi} - \frac{u}{\pi}\right)\Gamma\left(1 + \frac{2l\gamma}{\pi} - \frac{u}{\pi}\right)}{\Gamma\left(\frac{(2l+1)\gamma}{\pi} - \frac{u}{\pi}\right)\Gamma\left(1 + \frac{(2l-1)\gamma}{\pi} - \frac{u}{\pi}\right)} \,. \tag{2.1.4}
\end{aligned}$$

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This factor, together with the overall q-number factor, ensures that the S-matrix satisfies both crossing and unitarity constraints:

$$S_{dc}^{ab}(u) = S_{ad}^{bc}(\gamma - u) \tag{2.1.5}$$

$$\sum_{c'} S_{dc'}^{ab}(u)S_{dc}^{c'b}(-u) = \delta_{ac} \ . \tag{2.1.6}$$

Consider now the above scattering theory in the presence of a boundary denoted formally by $\mathbf{B}_a$, then the scattering between the kink and the boundary is described by the equation

$$K_{ab}(u)\mathbf{B}_a = \sum_c R_{ac}^b(u)K_{bc}(-u)\mathbf{B}_c \tag{2.1.7}$$

which can be given a graphical representation shown in Fig.(2). Notice that in this representation, the boundary naturally carries an RSOS spin.
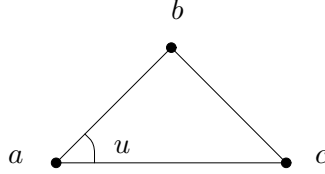

Figure 2: The boundary RSOS scattering matrix $R_{ac}^b(u)$

The function R_{ac}^b is called the boundary scattering matrix and satisfies the BYBE, which in the RSOS representation takes the form

$$\sum_{a',b'} R_{bb'}^a(u)S_{b'a'}^{ac}(u' + u)R_{b'b''}^{a'}(u')S_{b''a''}^{a'c}(u' - u) =$$

$$\sum_{a',b'} S_{ba'}^{ac}(u' - u)R_{bb'}^{a'}(u')S_{b'a''}^{a'c}(u' + u)R_{b'b''}^{a''}(u) \ . \tag{2.1.8}$$

This equation is illustrated graphically in Fig.(3).

In general, the function $R_{bc}^a(u)$ can be written as

$$R_{bc}^a(u) = \mathcal{R}(u) \left(\frac{[b][c]}{[a][a]} \right)^{-u/2\gamma} [\delta_{b \neq c}X_{bc}^a(u) + \delta_{bc}\{\delta_{b,a+1}U_a(u) + \delta_{b,a-1}D_a(u)\}] \tag{2.1.9}$$

where $\mathcal{R}(u)$ has to be determined from the boundary crossing and unitarity constraints, while X_{bc}^a and U_a, D_a have to be determined from the BYBE. An overall q-number factor
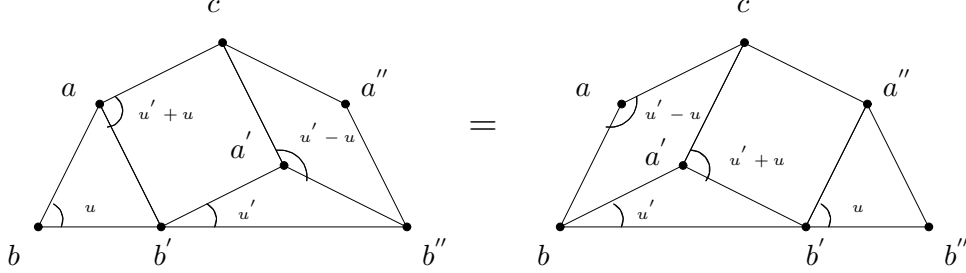
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Figure 3:   The boundary Yang-Baxter equation

has also been multiplied to the above to cancel that from the bulk S-matrix in order to simplify the BYBE. If X_{bc}^a does not vanish, the boundary R-matrix describes non-diagonal scattering process, otherwise the scattering is called diagonal. Note that due to the restriction that vacuum assumes value $1, \ldots, p-1$, $X_{bc}^1, X_{bc}^{p-1}, D_1, U_{p-1}$ are not defined. The case $p = 3$ has only diagonal scattering, so X_{bc}^a does not exist.

2.2   Non-diagonal scattering

We consider the scattering where the off-diagonal component X_{bc}^a is non-vanishing. To start, consider the case $b \neq c \neq b''$ in eqn.(2.1.8) where the BYBE gives

$$X_{a-1,a+1}^a(u')X_{a+1,a+3}^{a+2}(u) = X_{a-1,a+1}^a(u)X_{a+1,a+3}^{a+2}(u') \; ; 2 \leq a \leq p-4 \qquad (2.2.1)$$

which implies that $X_{a\pm1,a\mp1}^a$ can be written as

$$X_{a\pm1,a\mp1}^a(u) = h_\pm(u)X_\pm^a \qquad (2.2.2)$$

where $h_\pm(u)$ depends only on u and $X_\pm^a$ only on a.

On the other hand, the case $c = b = b'', a = a''$ gives

$$X_{a-1,a+1}^a(u')X_{a+1,a-1}^a(u) = X_{a-1,a+1}^a(u)X_{a+1,a-1}^a(u') \; ; 2 \leq a \leq p-2 \qquad (2.2.3)$$

which implies that

$$h_+(u')h_-(u) = h_+(u)h_-(u') \, , \qquad (2.2.4)$$

from which we conclude that

$$h_+(u) = (\text{const.})h_-(u) \, . \qquad (2.2.5)$$

Absorbing the constant in the above equation into X_-^a or X_+^a, we can make h_+ equal to h_- so that we can absorb the $h_\pm(u)$ into the overall $\mathcal{R}(u)$ factor and treat X_{bc}^a as u independent from now on.

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With this simplification, eqn.(2.1.8) can be broken down into the following independent equations in addition to the above two equations:

$$U'_a D_{a+2} f_+ \left(1 + f_- \frac{[a]}{[a+1]}\right) + D'_{a+2} D_{a+2} f_- \left(1 + f_+ \frac{[a+2]}{[a+1]}\right)$$

$$+ X^{a+2}_{a+1,a+3} X^{a+2}_{a+3,a+1} f_- = U_a D'_{a+2} f_+ \left(1 + f_- \frac{[a+2]}{[a+1]}\right)$$

$$+ U'_a U_a f_- \left(1 + f_+ \frac{[a]}{[a+1]}\right) + X^a_{a-1,a+1} X^a_{a+1,a-1} f_- \qquad (2.2.6)$$

for $1 \le a \le p-3$,

$$D'_{a+1} f_- \left(1 + f_+ \frac{[a+1]}{[a]}\right) + U'_{a-1} f_+ \left(1 + f_- \frac{[a-1]}{[a]}\right)$$

$$= U_{a-1} f_+ - U_{a+1} f_- \qquad (2.2.7)$$

$$U'_a f_- \left(1 + f_+ \frac{[a]}{[a+1]}\right) + D'_{a+2} f_+ \left(1 + f_- \frac{[a+2]}{[a+1]}\right)$$

$$= D_{a+2} f_+ - D_a f_- \qquad (2.2.8)$$

for $2 \le a \le p-3$, and

$$U'_{a-2} f_+ f_- \frac{[a][a-2]}{[a-1]^2} - U'_a + D'_a \left(1 + f_- \frac{[a]}{[a-1]}\right) \left(1 + f_+ \frac{[a]}{[a-1]}\right)$$

$$= D_a \left(1 + f_+ \frac{[a]}{[a-1]}\right) - U_a \left(1 + f_- \frac{[a]}{[a-1]}\right) \qquad (2.2.9)$$

$$D'_{a+2} f_+ f_- \frac{[a][a+2]}{[a+1]^2} - D'_a + U'_a \left(1 + f_- \frac{[a]}{[a+1]}\right) \left(1 + f_+ \frac{[a]}{[a+1]}\right)$$

$$= U_a \left(1 + f_+ \frac{[a]}{[a+1]}\right) - D_a \left(1 + f_- \frac{[a]}{[a+1]}\right) \qquad (2.2.10)$$

for $2 \le a \le p-2$. The last four equations are derived based on the assumption that the off-diagonal weight X^a_{bc} is **nonvanishing**. In the above equations, we used a compact notation where $U_a = U_a(u)$, $U'_a = U_a(u')$ (similarly for D_a) and

$$f_\pm = \sin(u' \pm u)/\sin(\gamma - u' \mp u) .$$

In addition, it should also be mentioned that the last term in the rhs (lhs) of eqn.(2.2.6) is present only when $a \ne 1(p-3)$ and the first terms of eqns.(2.2.9) and

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(2.2.10) are allowed only for $a \neq 2$ and $a \neq p - 2$, respectively. Let us call these terms that are not supposed to be there the "unwanted" terms. The way to solve these equations is to construct some recursion relations for the functions $U_a, D_a, X^a_{a\pm1,a\mp1}$ and solve the recursion relations subject to the conditions that the above mentioned "unwanted" terms are zero. Explicitly, one has

$$X^1_{0,2}X^1_{2,0} \quad = X^{p-1}_{p-2,p}X^{p-1}_{p,p-2} \quad = 0 \,, \tag{2.2.11}$$
$$U_0 \qquad = D_p \qquad = 0 \,. \tag{2.2.12}$$

A few comments are in order here. Notice that the coefficients of U_0 and D_p in eqns.(2.2.9), (2.2.10) are $[0]$ and $[p]$ respectively, which vanish by construction. So in principle, one needs not impose the above condition, eqn.(2.2.12), for the recursion relations of U_a, D_a. However, we shall see later that a particular solution of U_a, D_a is given by

$$U_a = -D_a = (\text{const.})\frac{1}{[a]} \tag{2.2.13}$$

which cancels the vanishing coefficients at $a = 0, p$, and renders the unwanted terms nonvanishing. Therefore, we have to impose eqn.(2.2.12) on the above solution.

Notice also that most of the above equations do not apply to the case $p = 4$, so we shall deal with this case separately.

From the above it is clear that eqns.(2.2.6)-(2.2.11) can be divided into two parts; eqn.(2.2.8)-eqn.(2.2.10) determine U_a and D_a while eqns.(2.2.6),(2.2.11) determine X^a_{bc}. Indeed, comparing eqn.(2.2.7) with eqn.(2.2.9) and similarly eqn.(2.2.8) with eqn.(2.2.10), we deduce that

$$(D'_a - D_a)\left(1 + f_+\frac{[a]}{[a-1]}\right) = (U'_{a-2} - U_{a-2})f_+\frac{[a]}{[a-1]}$$
$$+ (U'_a - U_a) \tag{2.2.14}$$
$$(U'_a - U_a)\left(1 + f_+\frac{[a]}{[a+1]}\right) = (D'_{a+2} - D_{a+2})f_+\frac{[a]}{[a+1]}$$
$$+ (D'_a - D_a) \,. \tag{2.2.15}$$

Substituting one into another, we get

$$\frac{(U'_{a+2} - U_{a+2}) - (U'_a - U_a)}{(U'_a - U_a) - (U'_{a-2} - U_{a-2})} = \frac{\sin\left((a+1)\gamma + u' + u\right)}{\sin\left((a-1)\gamma + u' + u\right)} \tag{2.2.16}$$

$$\frac{(D'_{a+2} - D_{a+2}) - (D'_a - D_a)}{(D'_a - D_a) - (D'_{a-2} - D_{a-2})} = \frac{\sin\left((a+1)\gamma - u' - u\right)}{\sin\left((a-1)\gamma - u' - u\right)} \tag{2.2.17}$$

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and writing the rhs respectively as

$$\frac{\cos\left(2u' + (a+1)\gamma\right) - \cos\left(2u + (a+1)\gamma\right)}{\cos\left(2u' + (a-1)\gamma\right) - \cos\left(2u + (a-1)\gamma\right)}$$

$$\frac{\cos\left(2u' - (a+1)\gamma\right) - \cos\left(2u - (a+1)\gamma\right)}{\cos\left(2u' - (a-1)\gamma\right) - \cos\left(2u - (a-1)\gamma\right)} \quad,$$

it is clear that

$$\begin{aligned}
U_{a+2}(u) - U_a(u) &= \cos\left(2u + (a+1)\gamma\right) + \beta'_a \\
D_{a+2}(u) - D_a(u) &= -\cos\left(2u - (a+1)\gamma\right) + \phi'_a
\end{aligned}$$

where β'_a, ϕ'_a are unknown functions of a only. Iterating the above, one finds

$$\begin{aligned}
U_a(u) &\propto \sin(2u + a\gamma) + \alpha(u) + \beta_a & (2.2.18) \\
D_a(u) &\propto \sin(2u - a\gamma) + \gamma(u) + \phi_a & (2.2.19)
\end{aligned}$$

where $\alpha(u), \gamma(u)$ are unknown functions of u, and β_a, ϕ_a of a. Furthermore, from eqns.(2.2.6)-(2.2.10), one can establish the following symmetry

$$U_a(u) = -D_a(-u) \, , \tag{2.2.20}$$

which reduces the number of unknown functions to two, namely, $\alpha(u)$ and β_a. To determine them, we have to substitute the above expressions for U_a, D_a back into eqns.(2.2.7)-(2.2.10). Notice, however, that these equations are linear in U_a, D_a, so it suffices to consider $\alpha(u)$ and β_a separately. Doing this amounts to finding special solutions to eqns.(2.2.7)-(2.2.10) where U_a, D_a have only u or a dependence. The solutions are given by

$$\alpha(u) = (\text{const.})\frac{1}{\sin(2u)} \, , \qquad\qquad \beta_a = (\text{const.})\frac{1}{\sin(a\gamma)} \tag{2.2.21}$$

respectively. Imposing eqn.(2.2.12) on $\alpha(u), \beta_a$, one finds

$$\beta_a = 0 \, . \tag{2.2.22}$$

So far the above U_a, D_a are obtained based on the assumption that the numerators and denominators of the lhs of eqns.(2.2.16),(2.2.17) are nonvanishing. In fact, there are

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additional solution to these recursion relations where the above mentioned numerators and denominators vanish;

$$
\begin{aligned}
U_{a+2}(u') - U_a(u') - U_{a+2}(u) + U_a(u) &= 0 \\
D_{a+2}(u') - D_a(u') - D_{a+2}(u) + D_a(u) &= 0 .
\end{aligned}
$$

The additional solution is given by

$$
U_a(u) = (\text{const.})\frac{\sin(a\gamma + 2u)}{\sin(2u)\sin(a\gamma)} , \qquad D_a(u) = (\text{const.})\frac{\sin(a\gamma - 2u)}{\sin(2u)\sin(a\gamma)} . \qquad (2.2.23)
$$

However, on imposing the condition eqn.(2.2.12), one finds that they have to be zero. In summary, the general non-diagonal solution to the four linear equations is given by

$$
\begin{aligned}
U_a(u) &= \sin(2u + a\gamma) + (\text{const.})\frac{1}{\sin(2u)} \\
D_{a+1}(u) &= \sin\left(2u - (a+1)\gamma\right) + (\text{const.})\frac{1}{\sin(2u)}
\end{aligned} \qquad (2.2.24)
$$

where $1 \leq a \leq p - 2$.

Having found U_a, D_a, the function X^a_{bc} can be easily obtained from eqn.(2.2.6), which can be further simplified with the symmetry properties given in eqn.(2.2.20) and taking u' to be $-u$ since X^a_{bc} does not depend on the rapidity. This gives

$$
X^{a+2}_{a+1,a+3}X^{a+2}_{a+3,a+1} - X^a_{a-1,a+1}X^a_{a+1,a-1} = D_{a+2}(u)U_{a+2}(u) - D_a(u)U_a(u) .
$$

Substituting U_a, D_a into the rhs and iterating the equations, we get

$$
X^a_{a-1,a+1}X^a_{a+1,a-1} = \sin^2\gamma - \sin^2(a\gamma) \qquad (2.2.25)
$$

where the use of eqn.(2.2.11) forces the first term to be $\sin^2\gamma$ and the coefficient of $\frac{1}{\sin(2u)}$ to vanish. Since this equation determines only the product, $X^a_{a-1,a+1}$ and $X^a_{a+1,a-1}$ are determined up to a gauge factor.

These solutions have the property that

$$
U_{p-a}(u) = -D_a(u) , \qquad X^{p-a}_{p-a-1,p-a+1}X^{p-a}_{p-a+1,p-a-1} = X^a_{a-1,a+1}X^a_{a+1,a-1} . \qquad (2.2.26)
$$

Next, we consider the BYBE for $p = 4$. The functions U_2, D_2 and X^2_{13}, X^2_{31} satisfy the following equations

$$
X^2_{13}(u')X^2_{31}(u) = X^2_{13}(u)X^2_{31}(u') \qquad (2.2.27)
$$

$$
\begin{aligned}
U_2\left(1 + \sqrt{2}f_-\right) + D'_2\left(1 + \sqrt{2}f_+\right)\left(1 + \sqrt{2}f_-\right) & \\
&= U'_2 + D_2\left(1 + \sqrt{2}f_+\right) \qquad (2.2.28)
\end{aligned}
$$

$$
\begin{aligned}
D_2\left(1 + \sqrt{2}f_-\right) + U'_2\left(1 + \sqrt{2}f_+\right)\left(1 + \sqrt{2}f_-\right) & \\
&= D'_2 + U_2\left(1 + \sqrt{2}f_+\right) . \qquad (2.2.29)
\end{aligned}
$$

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The functions U_1, D_3 are diagonal scattering components and do not couple to the above equations and we shall defer to next section for their computation. Here we have used the compact notation introduced earlier for U_a, D_a, and written out explicitly the rapidity dependence of X_{bc}^a. As before, the last two equations have been derived based on the assumption that X_{13}^2, X_{31}^2 are nonvanishing. From eqn.(2.2.27), we deduce that

$$X_{13}^2(u) = (\text{const.})X_{31}^2(u) . \tag{2.2.30}$$

We are free to take X_{31}^2 as unity and the above implies that X_{13}^2 is just a gauge factor, which we call g.

The rest of the equations can be turned into ordinary differential equations in the limit $u' \to u$, giving

$$\left(\dot{U}_2(u) + \dot{D}_2(u)\right)\tan(2u) + 2\left(U_2(u) + D_2(u)\right) = 0 \tag{2.2.31}$$

$$\left(\dot{U}_2(u) - \dot{D}_2(u)\right)\cot(2u) - 2\left(U_2(u) - D_2(u)\right) = 0 , \tag{2.2.32}$$

which can be integrated to give

$$U_2(u) = B/\sin(2u) + C\cos(2u) \tag{2.2.33}$$
$$D_2(u) = B/\sin(2u) - C\cos(2u) , \tag{2.2.34}$$

with B, C as free parameters.

This completes the determination of the non-diagonal solutions of the BYBE.

2.3 Diagonal scattering

For the diagonal scattering, we take

$$R_{bc}^a(u) = ([b]/[a])^{-u/\gamma}\mathcal{R}(u)\delta_{bc}\left[\delta_{b,a+1}U_a(u) + \delta_{b,a-1}D_a(u)\right] , \tag{2.3.1}$$

and the BYBE is equivalent to a single equation

$$
\begin{aligned}
U_{a-1}(u')D_{a+1}(u)&\sin(u' + u)\sin(a\gamma - u' + u) \\
&+ D_{a+1}(u')D_{a+1}(u)\sin(u' - u)\sin(a\gamma + u' + u) = \\
U_{a-1}(u)D_{a+1}(u')&\sin(u' + u)\sin(a\gamma + u' - u) \\
&+ U_{a-1}(u')U_{a-1}(u)\sin(u' - u)\sin(a\gamma - u' - u) ,
\end{aligned}
\tag{2.3.2}
$$

which holds only for $2 \leq a \leq p-2$. So the functions U_{p-2} and D_2 can not be determined from the BYBE. The above can be recast into

$$
\begin{aligned}
[\cos(a\gamma + 2u)Z(u) - \cos(a\gamma - 2u)][Z(u') - 1] = \\
[\cos(a\gamma + 2u')Z(u') - \cos(a\gamma - 2u')][Z(u) - 1]
\end{aligned}
\tag{2.3.3}
$$

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where

$$Z_a(u) \equiv D_{a+1}(u)/U_{a-1}(u) \; .$$

One can easily find that the general solution is

$$\frac{D_{a+1}(u)}{U_{a-1}(u)} = \frac{\sin(\xi_a + u)\sin(\xi_a + a\gamma - u)}{\sin(\xi_a - u)\sin(\xi_a + a\gamma + u)} \tag{2.3.4}$$

where ξ_a is a free parameter.

Thus for the diagonal solution, there are $p - 3$ parameters ξ_a. This solution gives $p - 1$ distinct diagonal scattering theories of kinks, each with a specific boundary $\mathbf{B}_a$. There is one free parameter ξ_a for each theory, except for the cases of $a = 1, p-1$ where there is no free parameter.

This solution includes a particular case of $p = 4$ which has been omitted earlier.

Further relations from boundary unitarity and crossing symmetry will be required to disentangle U_{a-1} and D_{a+1}, and determine U_2 and D_{p-2}, see later.

2.4 Boundary unitarity and crossing symmetry

The boundary unitarity and crossing symmetry conditions of the scattering matrix $R^a_{bc}(u)$ determine to some extent the overall factor $R(u)$. These conditions can be written as

$$\sum_c R^a_{bc}(u) R^a_{cd}(-u) = \delta_{bd} \tag{2.4.1}$$

$$\sum_d S^{ac}_{bd}(2u) R^d_{bc}(\gamma/2 + u) = R^a_{bc}(\gamma/2 - u) \; . \tag{2.4.2}$$

Consider the non-diagonal scattering $(p > 4)$ first. Substituting the expression for R^a_{bc} into the unitarity condition, we get the following

$$\mathcal{R}(u)\mathcal{R}(-u) \left[X^a_{bd} X^a_{db} \delta_{b \neq d} - U_a(u) D_a(u) \right] = 1$$

where use has been made of the symmetry eqn.(2.2.20). Applying the results eqns.(2.2.24), (2.2.25) to the above leads to

$$\mathcal{R}(u)\mathcal{R}(-u) \left(\sin^2 \gamma - 4\sin^2 u + 4\sin^4 u \right) = 1 \; . \tag{2.4.3}$$

While for crossing symmetry condition we get

$$\mathcal{U}(2u)\mathcal{R}(\gamma/2 + u)\sin(\gamma - 2u) = \mathcal{R}(\gamma/2 - u) \tag{2.4.4}$$

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using the relations

$$D_{a+2}(\gamma - u)\frac{[a+2]}{[a+1]} + U_a(\gamma - u)\frac{[a]}{[a+1]}$$
$$= f(2u)\left(U_a(u) - U_a(\gamma - u)\right) \tag{2.4.5}$$

$$U_a(\gamma - u)\frac{[a]}{[a+1]} + D_{a+2}(\gamma - u)\frac{[a+2]}{[a+1]}$$
$$= f(2u)\left(D_{a+2}(u) - D_{a+2}(\gamma - u)\right) \tag{2.4.6}$$

which are obtained from eqn.(2.2.8) in the limit $u' \to \gamma - u$. Here $f(u) = \sin u / \sin(\gamma - u)$.

The factor $\mathcal{R}(u)$ can be determined from eqns.(2.4.3), (2.4.4) up to the usual CDD ambiguity by separating $\mathcal{R}(u) = \mathcal{R}_0(u)\mathcal{R}_1(u)$ where $\mathcal{R}_0$ satisfies

$$\begin{aligned}
\mathcal{R}_0(u)\mathcal{R}_0(-u) &= 1 \\
\mathcal{U}(2u)\mathcal{R}_0(\gamma/2 + u)\sin(\gamma - 2u) &= \mathcal{R}_0(\gamma/2 - u) \ ,
\end{aligned} \tag{2.4.7}$$

whose minimal solution reads

$$R_0(u) = \frac{F_0(u)}{F_0(-u)} \tag{2.4.8}$$

where $F_l(u)$ has been given in eqn.(2.1.4). While $\mathcal{R}_1$ satisfies

$$\begin{aligned}
\mathcal{R}_1(u)\mathcal{R}_1(-u)\left(\sin^2\gamma - 4\sin^2 u + 4\sin^4 u\right) &= 1 \\
\mathcal{R}_1(u) &= \mathcal{R}_1(\gamma - u)
\end{aligned} \tag{2.4.9}$$

with minimum solution

$$\mathcal{R}_1(u) = \frac{1}{2}\sigma(\frac{\gamma}{2}, u)\sigma(\frac{\pi - \gamma}{2}, u) \tag{2.4.10}$$

where

$$\begin{aligned}
\sigma(x, u) &= \frac{\prod(x, \frac{\gamma}{2} - u)\prod(-x, \frac{\gamma}{2} - u)\prod(x, -\frac{\gamma}{2} + u)\prod(-x, -\frac{\gamma}{2} + u)}{\prod^2(x, \frac{\gamma}{2})\prod^2(-x, \frac{\gamma}{2})} \\[2mm]
\prod(x, u) &= \prod_{l=0}^{\infty}\frac{\Gamma\left(\frac{1}{2} + (2l + \frac{1}{2})\frac{\gamma}{\pi} + \frac{x}{\pi} - \frac{u}{\pi}\right)}{\Gamma\left(\frac{1}{2} + (2l + \frac{3}{2})\frac{\gamma}{\pi} + \frac{x}{\pi} - \frac{u}{\pi}\right)} \ .
\end{aligned} \tag{2.4.11}$$

For $p = 4$, the crossing symmetry condition is the same as eqn.(2.4.4), but unitarity now requires that

$$\mathcal{R}(u)\mathcal{R}(-u)\left(g + C^2\cos^2(2u) - B^2/\sin^2(2u)\right) = 1 \tag{2.4.12}$$

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These equations can again be solved by separation (see [17] for details). It should be remarked that there are two parameters in this case while there is only one in the higher p cases.

Next, we consider the diagonal case. For convenience, we set the undefined terms U_0, D_p to be zero. Unitarity and crossing symmetries relations give respectively

$$
\begin{array}{rcl}
\mathcal{R}(u)\mathcal{R}(-u)U_a(u)U_a(-u) & = & 1 \\
\mathcal{R}(u)\mathcal{R}(-u)D_{a+1}(u)D_{a+1}(-u) & = & 1
\end{array}
\tag{2.4.13}
$$

and

$$
\begin{aligned}
\mathcal{U}(\gamma - 2u)\mathcal{R}(\gamma - u)\,[U_a(\gamma - u)\sin\gamma\sin(a\gamma + 2u) & \\
+D_{a+2}(\gamma - u)\sin(\gamma - 2u)\sin((a+2)\gamma)] = \mathcal{R}(u)U_a(u)\sin((a+1)\gamma) & \\
\\
\mathcal{U}(\gamma - 2u)\mathcal{R}(\gamma - u)\,[D_{a+1}(\gamma - u)\sin\gamma\sin((a+1)\gamma - 2u) & \\
+U_{a-1}(\gamma - u)\sin(\gamma - 2u)\sin((a-1)\gamma)] = \mathcal{R}(u)D_{a+1}(u)\sin(a\gamma) &
\end{aligned}
\tag{2.4.14}
$$

for $1 \le a \le p - 2$.

These equations can be solved separately; we set

$$
\begin{array}{rcl}
\mathcal{R}(u)\mathcal{R}(-u) & = & 1 \\
\mathcal{U}(2u)\mathcal{R}(\gamma/2 + u)\sin(\gamma - 2u) & = & \mathcal{R}(\gamma/2 - u) \;,
\end{array}
\tag{2.4.15}
$$

so that $\mathcal{R}(u)$ has exactly the same solution as that of $\mathcal{R}_0(u)$ considered earlier. While U_a, D_a satisfy

$$
\begin{array}{rcl}
U_a(u)U_a(-u) & = & 1 \\
D_{a+1}(u)D_{a+1}(-u) & = & 1
\end{array}
\tag{2.4.16}
$$

and

$$
\begin{aligned}
U_a(\gamma - u)\sin\gamma\sin(a\gamma + 2u) + D_{a+2}(\gamma - u)\sin(\gamma - 2u)\sin((a+2)\gamma) & \\
= U_a(u)\sin(2u)\sin((a+1)\gamma)\;, & \\
D_{a+1}(\gamma - u)\sin\gamma\sin((a+1)\gamma - 2u) + U_{a-1}(\gamma - u)\sin(\gamma - 2u)\sin((a-1)\gamma) & \\
= D_{a+1}(u)\sin(2u)\sin(a\gamma)\;. &
\end{aligned}
\tag{2.4.17}
$$

for $1 \le a \le p - 2$. Substituting eqn.(2.3.4) into the above we get a relation between $U_a(u)\;(D_a(u))$ and $U_a(\gamma - u)\;(D_a(\gamma - u))$;

$$
\begin{array}{rcl}
\dfrac{U_{a-1}(u)}{U_{a-1}(\gamma - u)} & = & \dfrac{\sin(2(\gamma - u))\sin(\xi_a - u)\sin(\xi_a + a\gamma + u)}{\sin(2u)\sin(\xi_a - (\gamma - u))\sin(\xi_a + a\gamma + (\gamma - u))} \\
\\
\dfrac{D_{a+1}(u)}{D_{a+1}(\gamma - u)} & = & \dfrac{\sin(2(\gamma - u))\sin(\xi_a + u)\sin(\xi_a + a\gamma - u)}{\sin(2u)\sin(\xi_a + (\gamma - u))\sin(\xi_a + a\gamma - (\gamma - u))}\;.
\end{array}
\tag{2.4.18}
$$

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These relations together with eqn.(2.4.16) give the minimal solutions of $U_a(u)$ and $D_a(u)$

$$U_{a-1}(u) = \frac{1}{2}\sin 2(\gamma - u)\sin(\xi_a - u)\sin(\xi_a + a\gamma + u)\sigma(\gamma, u)$$
$$\times \sigma(\frac{\pi}{2} - \gamma, u)\sigma(\frac{\pi}{2} - \xi_a, u)\sigma(\frac{\pi}{2} - \xi_a - a\gamma, u) , \qquad (2.4.19)$$

$$D_{a+1}(u) = \frac{1}{2}\sin 2(\gamma - u)\sin(\xi_a + u)\sin(\xi_a + a\gamma - u)\sigma(\gamma, u)$$
$$\times \sigma(\frac{\pi}{2} - \gamma, u)\sigma(\frac{\pi}{2} - \xi_a, u)\sigma(\frac{\pi}{2} - \xi_a - a\gamma, u) . \qquad (2.4.20)$$

for $2 \leq a \leq p - 2$ and

$$U_{p-2}(u) = \frac{1}{2}\sin 2(\gamma - u)\sigma(\gamma, u)\sigma(\frac{\pi}{2} - \gamma, u) , \qquad (2.4.21)$$

$$D_2(u) = \frac{1}{2}\sin 2(\gamma - u)\sigma(\gamma, u)\sigma(\frac{\pi}{2} - \gamma, u) . \qquad (2.4.22)$$

To summarize, there are two classes of solutions to the BYBE; diagonal and non-diagonal. Unlike the solution in vertex representation, the former is not a special limit of the latter. In fact, the diagonal solution carries $p - 3$ free parameters while nondiagonal has non.

2.5 Comments on the SOS model

We have considered from the start heights take values from 1 to $p-1$, which is necessary for the bulk scattering weights to be finite as the parameter $\pi/\gamma = p$ is a positive integer. When π/γ is not a rational number, there is no bounds on the heights and the corresponding representation is known as solid-on-solid (SOS). The removal of the heights' restriction certainly affects the solution of the BYBE.

For the diagonal solution, it is clear that essentially there is no difference between the SOS and RSOS solution, where the SOS solution is given by eqns.(2.4.19),(2.4.20) for any integer a and the overall factor $\mathcal{R}(u)$ is the same as before. Hence there is a free parameter for each height.

While for the non-diagonal solution, the conditions eqns.(2.2.11),(2.2.12) of the recursion relations do not apply at all, thus $\beta_a \neq 0$ and the corresponding diagonal weights are given by

$$U_a(u) = c_1 \sin(2u + a\gamma) + c_2\frac{1}{\sin(a\gamma)} + c_3\frac{\sin(a\gamma + 2u)}{\sin(2u)\sin(a\gamma)} + c_4\frac{1}{\sin(2u)}$$
$$\qquad (2.5.1)$$
$$D_a(u) = c_1 \sin(2u - a\gamma) - c_2\frac{1}{\sin(a\gamma)} + c_3\frac{\sin(a\gamma - 2u)}{\sin(2u)\sin(a\gamma)} + c_4\frac{1}{\sin(2u)}$$

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where c_i ; $i = 1, \ldots, 4$ are free parameters. The off-diagonal weights satisfy

$$
\begin{aligned}
X^a_{a-1,a+1} X^a_{a+1,a-1} = \ & c_0^2 + 2c_1 c_4 \cos(a\gamma) - c_1^2 \sin^2(a\gamma) - c_2^2 \frac{1}{\sin^2(a\gamma)} \\
& - 2c_2 c_3 \frac{\cos(a\gamma)}{\sin^2(a\gamma)} - c_3^2 \frac{1}{\sin^2(a\gamma)}
\end{aligned}
\tag{2.5.2}
$$

and are determined up an additive constant c_0. Of these five free parameters one is an overall factor, so there are four free parameters in this case. The overall factor $\mathcal{R}_0$ is given as before, but $\mathcal{R}_1(u)$ now contains all the information of the boundary conditions and has to satisfy

$$
\begin{aligned}
& \mathcal{R}_1(u)\mathcal{R}_1(-u) \left(c_0^2 - c_1^2 \sin^2(2u) + 2c_1 c_2 \cos(2u) - \frac{c_3^2 + 2c_3 c_4 \cos(2u) + c_4^2}{\sin^2(2u)} \right) = 1 \\
& \mathcal{R}_1(u) = \mathcal{R}_1(\gamma - u)
\end{aligned}
\tag{2.5.3}
$$

whose minimum solution is

$$
\mathcal{R}_1(u) = \frac{2\sigma(\vartheta_1, u)\sigma(\vartheta_2, u)\sigma(\vartheta_3, u)\sigma(\vartheta_4, u)}{(c_3 + c_4)\sigma(0, u)} \mathcal{S}(u)
\tag{2.5.4}
$$

where ϑ_i are related to c_i via

$$
\begin{aligned}
\prod_{i=1}^4 \cos^2 \vartheta_1 &= \left(\frac{c_3 + c_4}{4c_1} \right)^2 , \\
\sum_{i<j<k=1}^4 \cos^2 \vartheta_i \cos^2 \vartheta_j \cos^2 \vartheta_k &= \frac{c_0^2 + c_3 c_4 + 2c_1 c_2}{4c_1^2} , \\
\sum_{i<j=1}^4 \cos^2 \vartheta_i \cos^2 \vartheta_j &= \frac{c_0^2 + 5c_1 c_2 + 4c_1^2}{4c_1^2} , \\
\sum_{i=1}^4 \cos^2 \vartheta_i &= \frac{c_1 c_2 + 2c_1^2}{c_1^2}
\end{aligned}
$$

and $\sigma(x, u)$ has been given before, while

$$
\mathcal{S}(u) = \prod_{l=0}^\infty \frac{\Gamma\left((2l+1)\frac{\gamma}{\pi} + \frac{u}{\pi}\right) \Gamma\left((2l+2)\frac{\gamma}{\pi} + \frac{u}{\pi}\right) \Gamma\left(1 - (2l+1)\frac{\gamma}{\pi} - \frac{u}{\pi}\right) \Gamma\left(1 - (2l+2)\frac{\gamma}{\pi} - \frac{u}{\pi}\right)}{\Gamma\left((2l+1)\frac{\gamma}{\pi} - \frac{u}{\pi}\right) \Gamma\left((2l+2)\frac{\gamma}{\pi} - \frac{u}{\pi}\right) \Gamma\left(1 - (2l+1)\frac{\gamma}{\pi} + \frac{u}{\pi}\right) \Gamma\left(1 - (2l+2)\frac{\gamma}{\pi} + \frac{u}{\pi}\right)} .
\tag{2.5.5}
$$

It is interesting to point out that the c_2, c_3, c_4 terms in U_a, D_a are related to the boundary K-matrix of the 6-vertex model[21] via the vertex-SOS intertwiner[22, 20, 23]. In

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this light, one can regard the term c_1 to be the solution special to the SOS/RSOS representation of the BYBE. In fact, it is not clear whether there exist an intertwiner that relate it to the K-matrix of the 6-vertex model. It is then natural to wonder if similar special solution occur in the elliptic case[24].

Also intriguing is that restricting SOS to RSOS corresponds to

$$c_2 = c_3 = c_4 = 0, \qquad c_0 = c_1 \sin(a\gamma) . \tag{2.5.6}$$

3 Commuting transfer matrix

Following the technique proposed in [2] for the vertex model, one can similarly construct a family of commuting transfer matrix for the RSOS/SOS model with boundary.

To start, it can be shown that if R^a_{bc} is a solution to the BYBE in the RSOS/SOS form then the following combination

$$\sum_a S^{fe}_{ba}(u - u_1) S^{ae}_{cd}(u + u_1) R^a_{bc}(u) \tag{3.1}$$

also satisfies the BYBE, where $S^{fe}_{ba}(u)$ is the solution of the bulk YBE given in eqn.(2.1.2) and u_1 is an arbitrary parameter. The proof is essentially the same as the vertex case given in [2] and we shall not repeat it here.

It is convenient to think of the BYBE as the defining relation of some associative algebra generated by the symbol R^a_{bc}. So the solutions given in the previous section correspond to particular representations of this algebra where the "quantum space" is trivial and the auxiliary space is the space of a one-step path $\mathcal{P}_1$ on a truncated Bratteli diagram with ab and ac being in- and out-state, respectively. In this context, the above "decorated" solution then corresponds to a representation whose quantum space is isomorphic to $\mathcal{P}_1$ that is formed by the nodes f, b (d, c). Clearly, the above construction can be repeated for an arbitrary number of times (say $N + 1$) giving a boundary R-matrix that acts on $\mathcal{P}_N$, the collection of N-step paths on a truncated Bratteli diagram. We shall denote such a solution as $\mathbf{R}^a_{bc}$ which should be regarded as an operator acting on $\mathcal{P}_N$. Its matrix element is explicitly given by

$$
\mathbf{R}^a_{bc}(u)_{a_0,\cdots,a_N;a_0'',\cdots,a_N''} = \delta_{aa_N'} \delta_{ba_N} \delta_{ca_N''} \prod_{i=1}^{N} \sum_{a_{i-1}'} \left(S^{a_i a_i'}_{a_{i-1} a_{i-1}'}(u - u_i) \right.
$$
$$
\left. \times S^{a_{i-1}' a_i'}_{a_{i-1}'' a_i''}(u + u_i) \right) R^{a_0'}_{a_0 a_0''}(u) \tag{3.2}
$$

which has the graphical representation given in Fig.(4). It carries N parameters u_i
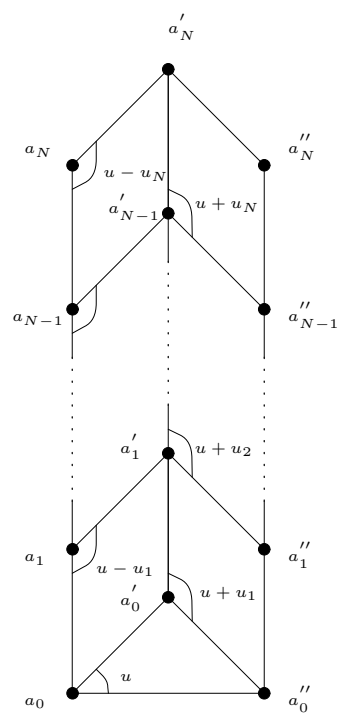
Figure 4: "Decorated" boundary scattering matrix

from the bulk S-matrices and additional ones from R_{bc}^a. To form a commuting transfer matrix out of $\mathbf{R}_{bc}^a$, like in the vertex case, one has to combine it with another BYBE solution (denoted here as $\tilde{R}$) as follows

$$\mathbf{T}(u)_{a_0,\cdots,a_N;a_0'',\cdots,a_N''} \equiv \sum_{a,b,c} \tilde{R}_{cb}^a(u)\mathbf{R}_{b,c}^a(u)_{a_0,\cdots,a_N;a_0'',\cdots,a_N''} \; . \tag{3.3}$$

Hence the transfer matrix $\mathbf{T}(u)$ is again an operator acting on $\mathcal{P}_N$.

To show that

$$[\mathbf{T}(u), \mathbf{T}(u')] = 0 \; ,$$

one inserts four bulk S-matrices using the unitarity condition

$$\sum_{\alpha} S_{b\alpha}^{ac}(u'+u)S_{bd}^{\alpha c}(-u'-u) \propto \delta_{ac} \; ,$$

and the crossing-unitarity condition

$$\sum_{\alpha} S_{cd}^{b\alpha}(u'+u)S_{ab}^{d\alpha}(\gamma-u+\gamma-u') \propto \delta_{ac} \; ,$$

into $\mathbf{T}(u)\mathbf{T}(u')$. Then, one uses the BYBE to permute the $\mathbf{R}$'s, and the $\tilde{R}$'s. Because of the argument $\gamma-u+\gamma-u'$ that appears in the crossing-unitarity condition, one can take

$$\tilde{R}_{bc}^a(u) \equiv R_{bc}^a(\gamma-u) \; . \tag{3.4}$$

4 Diagonalization of the Transfer matrix

So far, we managed to obtain solutions to the BYBE and construct the corresponding commuting transfer matrix. It would be necessary to diagonalize the transfer matrix in order to study the statistical models given by these solutions. For applications to field theory, diagonalization of the transfer matrix is also needed in order to write down the thermodynamic Bethe ansatz equation. For this purpose, a systematic approach generalizing the algebraic Bethe ansatz for the case of the periodic boundary condition has been devised in [2]. However, the method relies upon the conservation of the S^z in the vertex language and is thus applicable only to diagonal boundary scattering theories. Therefore, we shall consider only the diagonal scattering solution and adapt the algebraic Bethe ansatz method devised in [2], along the line of [19], to the SOS model with boundary. The algebraic Bethe ansatz relies upon the existence of some pseudo-vacuum, which in the vertex model, is a state with either all spins equal to $1/2$ or $-1/2$. In the SOS model, such a state corresponds to a path which takes the form

of a 45°-oriented straight line in the Bratteli diagram. It is obvious that some heights on such a path, for lattice size N large enough $(> p)$, have to exceed the bounds 1 or $p - 1$. Therefore, this pseudo-vacuum does not belong to the **truncated** Bratteli diagram and the algebraic Bethe ansatz that we are going to use is applicable to the SOS model only. For consistency, we have to assume that γ/π is an irrational number.

To diagonalize the transfer matrix given in eqn.(3.3), we have to first write down the algebraic relations satisfied by $\mathbf{R}_{bc}^a$. As before, we express the operator $\mathbf{R}_{bc}^a$ as follows

$$
\begin{aligned}
\mathbf{R}_{bc}^a(u) &= \mathcal{R}_N(u) \left(\frac{[b][c]}{[a][a]} \right)^{-u/2\gamma} \prod_{j=2}^{N} \left(\frac{[a_j'']}{[a_j]} \right)^{(u_j - u_{j-1})/2\gamma} (\delta_{b \neq c} \mathbf{X}_{bc}^a(u) \\
&\quad + \delta_{bc}(\delta_{b,a+1} \mathbf{U}_a(u) + \delta_{b,a-1} \mathbf{D}_a(u)))
\end{aligned}
\tag{4.1}
$$

where

$$
\mathcal{R}_N(u) = \mathcal{R}(u) \prod_{i=1}^{N} \mathcal{U}(u - u_i)\mathcal{U}(u + u_i) \, ,
$$

which, along with q-number factors, ensures the boundary crossing and unitarity symmetry of $\mathbf{R}_{bc}^a$. Here $\mathbf{X}_{bc}^a, \mathbf{U}_a, \mathbf{D}_a$ are now non-commutative operators that satisfy the algebraic relations encoded by the BYBE. (see appendix) Because $\tilde{R}_{bc}^a$ is diagonal, the commuting transfer matrix can be written as

$$
\begin{aligned}
\mathbf{T}(u) &= \mathcal{R}(\gamma - u)\mathcal{R}_N(u) \prod_{j=1}^{N-1} \left(\frac{[a_j'']}{[a_j]} \right)^{(u_j - u_{j+1})/2\gamma} \left(\frac{[b-1]}{[b]} U_{b-1}(\gamma - u)\mathbf{U}_{b-1}(u) \right. \\
&\quad \left. + \frac{[b+1]}{[b]} D_{b+1}(\gamma - u)\mathbf{D}_{b+1}(u) \right) \, .
\end{aligned}
\tag{4.2}
$$

It is important to bear in mind that the RSOS heights a_0, a_0'' on the "bottom" boundary (see Fig.(4)) are set to be the same since we consider only diagonal scattering. Let us denote them as a, while the heights on the other boundary are taken to be b as evident from the above equation. Hence the statistical model associated with the transfer matrix is the one defined on a square lattice whose boundary heights are shown in Fig.(5), where heights denoted by open-circles are summed over.

Consider the column of heights in Fig.(4) where $a_j = a + j$ and denote this state as ω_a^{a+N}. By construction, ω_a^{a+N} is an eigenstate of $\mathbf{U}_{a+N-1}(u)$ and $\mathbf{D}_{a+N+1}(u)$ since the top and bottom heights of $\mathbf{U}_{a+N-1}(u)\omega_a^{a+N}$ and $\mathbf{D}_{a+N+1}(u)\omega_a^{a+N}$ are $a + N$ and a respectively. Furthermore, it is annihilated by $\mathbf{X}_{a+N+2,a+N}^{a+N+1}(u)$ due to the constraint that neighboring heights differ by ± 1. Explicitly,

$$
\mathbf{U}_{a+N-1}(u)\omega_a^{a+N} = \mathcal{U}_a^N(u)\omega_a^{a+N}
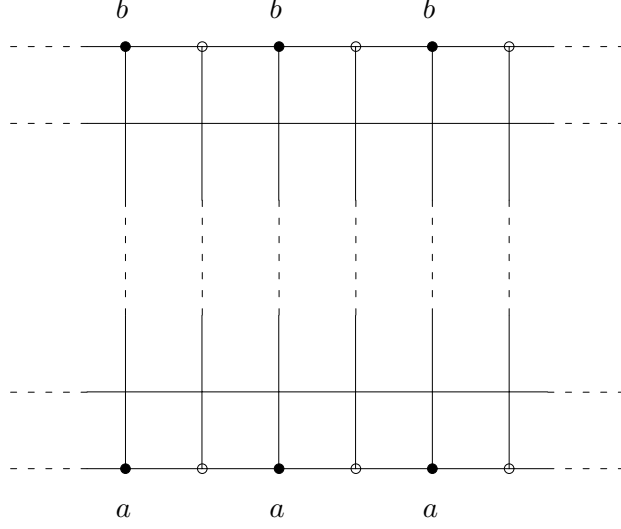$$

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Figure 5: Lattice generated by the transfer matrix

$$
\begin{aligned}
\mathbf{D}_{a+N+1}(u)\omega_a^{a+N} &= \mathcal{D}_a^N(u)\omega_a^{a+N} \\
\mathbf{X}_{a+N+2,a+N}^{a+N+1}(u)\omega_a^{a+N} &= 0
\end{aligned}
\tag{4.3}
$$

where the eigenvalues are given by

$$
\begin{aligned}
\mathcal{U}_a^N(u) &= \sum_{j=1}^N \left(\prod_{i=j+1}^N \mathcal{A}_{a+i}(u_i)\right) \mathcal{B}_{a+j}(u_j) \left(\prod_{k=1}^{j-1} \mathcal{C}_{a+k}(u_k)\right) D_{a+1}(u) \\
&\quad + \prod_{j=1}^N \mathcal{A}_{a+j}(u_j) U_{a-1}(u) \\
\mathcal{D}_a^N(u) &= \prod_{j=1}^N \mathcal{C}_{a+j}(u_i) D_{a+1}(u)
\end{aligned}
\tag{4.4}
$$

with

$$
\begin{aligned}
\mathcal{A}_{a+i}(u_i) &\equiv \frac{\sin((a+i)\gamma)\sin((a+i-2)\gamma)\sin(u-u_i)\sin(u+u_i)}{\sin^2((a+i-1)\gamma)} \\
\mathcal{B}_{a+i}(u_i) &\equiv \frac{\sin^2\gamma \sin((a+i-1)\gamma+u-u_i)\sin((a+i-1)\gamma+u+u_i)}{\sin^2((a+i-1)\gamma)} \\
\mathcal{C}_{a+i}(u_i) &\equiv \sin(\gamma-u+u_i)\sin(\gamma-u-u_i)
\end{aligned}
$$

and $U_{a-1}(u), D_{a+1}(u)$ are given by eqns.(2.4.19),(2.4.20).

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The state $\mathbf{X}^{a+N-1}_{a+N-2,a+N}(\lambda)\omega^{a+N}_a$ is non-zero, which corresponds to a column of spins where the "bottom" and "top" spins have heights a and $a + N - 2$ respectively. So to obtain a state whose top spin has height given by b, one has to act on ω^{a+N}_a successively with $M \equiv (N + a - b)/2$ operators $\mathbf{X}^{a+N-i}_{a+N-i-1,a+N-i+1}(\lambda_i)$, $i = 1, \cdots, M$. We shall denote such a state as

$$\psi^b_a(\vec{\lambda}) \equiv \mathbf{X}^{b+1}_{b,b+2}(\lambda_1)\cdots\mathbf{X}^{a+N-1}_{a+N-2,a+N}(\lambda_M)\omega^{a+N}_a \tag{4.5}$$

which is the Bethe ansatz state, and the set of parameters $\vec{\lambda} \equiv (\lambda_1, \cdots, \lambda_M)$ have to satisfy some consistency condition necessary for $\psi^b_a(\vec{\lambda})$ to be an eigenstate of the transfer matrix. Notice that M is always an integer fixed by the heights a, b and N.

The algebraic relations among $\mathbf{X}^a_{a\pm1,a\mp1}, \mathbf{U}_a, \mathbf{D}_a$ necessary for our purpose are (see Appendix)

$$\begin{aligned}
\mathbf{U}_{a-1}(u')\mathbf{X}^{a+1}_{a,a+2}(u) &= g_{1a}(u',u)\mathbf{X}^{a+1}_{a,a+2}(u)\mathbf{U}_{a+1}(u') + g_{2a}(u',u)\mathbf{X}^{a+1}_{a,a+2}(u')\mathbf{U}_{a+1}(u) \\
&+ g_{3a}(u',u)\mathbf{X}^{a+1}_{a,a+2}(u')\mathbf{D}_{a+3}(u) + g_{4a}(u',u)\mathbf{X}^{a+1}_{a,a+2}(u)\mathbf{D}_{a+3}(u') \\
\mathbf{D}_{a+1}(u')\mathbf{X}^{a+1}_{a,a+2}(u) &= f_{1a}(u',u)\mathbf{X}^{a+1}_{a,a+2}(u)\mathbf{D}_{a+1}(u') + f_{2a}(u',u)\mathbf{X}^{a+1}_{a,a+2}(u')\mathbf{D}_{a+1}(u) \\
&+ f_{3a}(u',u)\mathbf{X}^{a+1}_{a,a+2}(u')\mathbf{U}_{a+1}(u) ,
\end{aligned} \tag{4.6}$$

where

$$\begin{aligned}
g_{1a}(u',u) &= -\frac{\sin(a\gamma)\sin((a+1)\gamma)\sin(\gamma - u' + u)\sin(2\gamma - u' - u)}{\sin((a-1)\gamma)\sin((a+2)\gamma)\sin(\gamma - u' - u)\sin(u' - u)} \\
g_{2a}(u',u) &= \frac{\sin\gamma\sin((a+1)\gamma)\sin(a\gamma + u' - u)\sin(2\gamma - u' - u)}{\sin((a-1)\gamma)\sin((a+2)\gamma)\sin(\gamma - u' - u)\sin(u' - u)} \\
g_{3a}(u',u) &= -\frac{\sin\gamma\sin((a+1)\gamma)\sin(a\gamma + u' + u)\sin(2\gamma - u' + u)}{\sin((a-1)\gamma)\sin((a+2)\gamma)\sin(\gamma - u' - u)\sin(u' - u)} \\
g_{4a}(u',u) &= \frac{\sin\gamma\sin(2\gamma)\sin(a\gamma + u' + u)\sin((a+1)\gamma + u' - u)}{\sin((a-1)\gamma)\sin((a+2)\gamma)\sin(\gamma - u' - u)\sin(u' - u)} \\
f_{1a}(u',u) &= -\frac{\sin(u' + u)\sin(\gamma + u' - u)}{\sin(\gamma - u' - u)\sin(u' - u)} \\
f_{2a}(u',u) &= \frac{\sin\gamma\sin(u' + u)\sin((a+2)\gamma - u' + u)}{\sin((a+2)\gamma)\sin(\gamma - u' - u)\sin(u' - u)} \\
f_{3a}(u',u) &= -\frac{\sin\gamma\sin((a+2)\gamma - u' - u)}{\sin((a+2)\gamma)\sin(\gamma - u' - u)}
\end{aligned}$$

The action of the transfer matrix on the state $\psi^b_a(\vec{\lambda})$ can be evaluated by commuting $\mathbf{U}_{b-1}(u)$ and $\mathbf{D}_{b+1}(u)$ through $\mathbf{X}^{a+N-i}_{a+N-i-1,a+N+i-1}(\lambda_i)$. However, the presence of the

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$g_{4a}(u^{'}, u)$ term in the first commutation relation complicates matters considerably. Like the vertex case, it is desirable to define a new operator

$$\tilde{\mathbf{U}}_{a-1}(u) \equiv \mathbf{U}_{a-1}(u) + h_a(u)\mathbf{D}_{a+1}(u) \tag{4.7}$$

with

$$h_a(u) = -\frac{\sin\gamma\sin((a-1)\gamma + 2u)}{\sin((a-1)\gamma)\sin(\gamma - 2u)} .$$

so that the operators $\tilde{\mathbf{U}}_{a-1}(u), \mathbf{D}_{a+1}(u)$ satisfy simplified relations

$$
\begin{aligned}
\tilde{\mathbf{U}}_{a-1}(u^{'})\mathbf{X}_{a,a+2}^{a+1}(u) &= \alpha_{1a}(u^{'}, u)\mathbf{X}_{a,a+2}^{a+1}(u)\tilde{\mathbf{U}}_{a+1}(u^{'}) + \alpha_{2a}(u^{'}, u)\mathbf{X}_{a,a+2}^{a+1}(u^{'})\tilde{\mathbf{U}}_{a+1}(u) \\
&\quad + \alpha_{3a}(u^{'}, u)\mathbf{X}_{a,a+2}^{a+1}(u^{'})\mathbf{D}_{a+3}(u) \tag{4.8} \\
\mathbf{D}_{a+1}(u^{'})\mathbf{X}_{a,a+2}^{a+1}(u) &= \beta_{1a}(u^{'}, u)\mathbf{X}_{a,a+2}^{a+1}(u)\mathbf{D}_{a+1}(u^{'}) + \beta_{2a}(u^{'}, u)\mathbf{X}_{a,a+2}^{a+1}(u^{'})\mathbf{D}_{a+1}(u) \\
&\quad + \beta_{3a}(u^{'}, u)\mathbf{X}_{a,a+2}^{a+1}(u^{'})\tilde{\mathbf{U}}_{a+1}(u) , \tag{4.9}
\end{aligned}
$$

where

$$
\begin{aligned}
\alpha_{1a}(u^{'}, u) &= -\frac{\sin(a\gamma)\sin((a+1)\gamma)\sin(\gamma - u^{'} + u)\sin(2\gamma - u^{'} - u)}{\sin((a-1)\gamma)\sin((a+2)\gamma)\sin(\gamma - u^{'} - u)\sin(u^{'} - u)} \\
\alpha_{2a}(u^{'}, u) &= \frac{\sin\gamma\sin(a\gamma)\sin((a+1)\gamma + u^{'} - u)\sin(2\gamma - 2u)}{\sin((a-1)\gamma)\sin((a+2)\gamma)\sin(\gamma - 2u^{'})\sin(u^{'} - u)} \\
\alpha_{3a}(u^{'}, u) &= -\frac{\sin\gamma\sin(a\gamma)\sin(2u)\sin(a\gamma + u^{'} + u)\sin(2\gamma - 2u^{'})}{\sin((a-1)\gamma)\sin((a+1)\gamma)\sin(\gamma - u^{'} - u)\sin(\gamma - 2u^{'})} \\
\beta_{1a}(u^{'}, u) &= -\frac{\sin(u^{'} + u)\sin(\gamma + u^{'} - u)}{\sin(\gamma - u^{'} - u)\sin(u^{'} - u)} \\
\beta_{2a}(u^{'}, u) &= \frac{\sin\gamma\sin(2u)\sin((a+1)\gamma - u^{'} + u)}{\sin((a+1)\gamma)\sin(\gamma - 2u)\sin(u^{'} - u)} \\
\beta_{3a}(u^{'}, u) &= -\frac{\sin\gamma\sin((a+2)\gamma - u^{'} - u)}{\sin((a+2)\gamma)\sin(\gamma - u^{'} - u)} .
\end{aligned}
$$

Moreover the eigenvalue $\tilde{\mathcal{U}}_a^N(u)$ of $\tilde{\mathbf{U}}_{a-1}(u)$ on ω_a^{a+N} is much simplified and given by

$$\tilde{\mathcal{U}}_a^N(u) = -\frac{\sin(a\gamma)\sin(2u)\sin(\xi_a + (a-1)\gamma + u)\sin(\xi_a + \gamma - u)}{\sin((a-1)\gamma)\sin(\gamma - 2u)\sin(\xi_a + a\gamma + u)\sin(\xi_a - u)}\prod_{j=1}^{N}\mathcal{A}_{a+j}(u_j)U_{a-1}(u) \tag{4.10}$$

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where use has been made of the relation

$$\mathcal{B}_{a+i}(u_i) + h_{a+i}(u)\mathcal{C}_{a+i}(u_i) = h_{a+i-1}(u)\mathcal{A}_{a+i}(u_i). \tag{4.11}$$

Another important relation we need is

$$\mathbf{X}^{a+1}_{a,a+2}(u)\mathbf{X}^{a+3}_{a+2,a+4}(u^{'}) = \mathbf{X}^{a+1}_{a,a+2}(u^{'})\mathbf{X}^{a+3}_{a+2,a+4}(u) \tag{4.12}$$

which implies that the Bethe ansatz state $\psi_a^b(\vec{\lambda})$ is a symmetric function in the λ_i's, which is useful in obtaining the Bethe ansatz equation.

It is now straight forward to compute the action of $\tilde{\mathbf{U}}_{b-1}(u), \mathbf{D}_{b+1}(u)$ on $\psi_a^b(\vec{\lambda})$ giving

$$
\begin{aligned}
\tilde{\mathbf{U}}_{b-1}(u)\psi_a^b(\vec{\lambda}) \quad &= \alpha_{1b}(u,\lambda_1)\alpha_{1b+2}(u,\lambda_2)\cdots\alpha_{1a+N-2}(u,\lambda_M)\tilde{\mathcal{U}}_a^N(u)\psi_a^b(\vec{\lambda}) \\
&+ \Big[\alpha_{2b}(u,\lambda_1)\alpha_{1b+2}(\lambda_1,\lambda_2)\cdots\alpha_{1a+N-2}(\lambda_1,\lambda_M)\tilde{\mathcal{U}}_a^N(\lambda_1) \\
&+ \alpha_{3b}(u,\lambda_1)\beta_{1b+2}(\lambda_1,\lambda_2)\cdots\beta_{1a+N-2}(\lambda_1,\lambda_M)\mathcal{D}_a^N(\lambda_1)\Big]\,\psi_a^b(\vec{\lambda};\lambda_1) \\
&+ \cdots \\
&+ \Big[\alpha_{2b}(u,\lambda_M)\alpha_{1b+2}(\lambda_M,\lambda_2)\cdots\alpha_{1a+N-2}(\lambda_M,\lambda_{M-1})\tilde{\mathcal{U}}_a^N(\lambda_M) \\
&+ \alpha_{3b}(u,\lambda_M)\beta_{1b+2}(\lambda_M,\lambda_2)\cdots\beta_{1a+N-2}(\lambda_M,\lambda_{M-1})\mathcal{D}_a^N(\lambda_M)\Big]\,\psi_a^b(\vec{\lambda};\lambda_M)
\end{aligned}
\tag{4.13}
$$

and

$$
\begin{aligned}
\mathbf{D}_{b+1}(u)\psi_a^b(\vec{\lambda}) \quad &= \beta_{1b}(u,\lambda_1)\beta_{1b+2}(u,\lambda_2)\cdots\beta_{1a+N-2}(u,\lambda_M)\mathcal{D}_a^N(u)\psi_a^b(\vec{\lambda}) \\
&+ \Big[\beta_{2b}(u,\lambda_1)\beta_{1b+2}(\lambda_1,\lambda_2)\cdots\beta_{1a+N-2}(\lambda_1,\lambda_M)\mathcal{D}_a^N(\lambda_1) \\
&+ \beta_{3b}(u,\lambda_1)\alpha_{1b+2}(\lambda_1,\lambda_2)\cdots\alpha_{1a+N-2}(\lambda_1,\lambda_M)\tilde{\mathcal{U}}_a^N(\lambda_1)\Big]\,\psi_a^b(\vec{\lambda};\lambda_1) \\
&+ \cdots \\
&+ \Big[\beta_{2b}(u,\lambda_M)\beta_{1b+2}(\lambda_M,\lambda_2)\cdots\beta_{1a+N-2}(\lambda_M,\lambda_{M-1})\mathcal{D}_a^N(\lambda_M) \\
&+ \beta_{3b}(u,\lambda_M)\alpha_{1b+2}(\lambda_M,\lambda_2)\cdots\alpha_{1a+N-2}(\lambda_M,\lambda_{M-1})\tilde{\mathcal{U}}_a^N(\lambda_M)\Big]\,\psi_a^b(\vec{\lambda};\lambda_M)\,,
\end{aligned}
\tag{4.14}
$$

where the state $\psi_a^b(\vec{\lambda};\lambda_i)$ is defined as in eqn.(4.5) with λ_i replaced by u. Combining the above in the transfer matrix (see eqn.(4.2)),

$$
\begin{aligned}
\mathbf{T}(u) \quad \propto \quad &\frac{\sin(2\gamma - 2u)\sin(\xi_b - u)\sin(\xi_b + b\gamma + u)D_{b+1}(\gamma - u)}{\sin(\gamma - 2u)\sin(\xi_b + \gamma - u)\sin(\xi_b + (b-1)\gamma + u)}\mathbf{D}_{b+1}(u) \\
&+ \frac{\sin((b-1)\gamma)U_{b-1}(\gamma - u)}{\sin(b\gamma)}\tilde{\mathbf{U}}_{b-1}(u)\,,
\end{aligned}
\tag{4.15}
$$

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the state $\psi_a^b(\vec{\lambda})$ is an eigenstate of the transfer matrix if the coefficients of $\psi_a^b(\vec{\lambda}; \lambda_i)$, $i = 1, \cdots, M$ vanish, which gives the following Bethe ansatz equation to be satisfied for λ_i's

$$\frac{\sin(\xi_b - \gamma + \lambda_i)\sin(\xi_b + (b+1)\gamma - \lambda_i)\sin(\xi_a + \gamma - \lambda_i)\sin(\xi_a + (a-1)\gamma + \lambda_i)}{\sin(\xi_b - \lambda_i)\sin(\xi_b + b\gamma + \lambda_i)\sin(\xi_a + \lambda_i)\sin(\xi_a + a\gamma - \lambda_i)}$$

$$= \prod_{\substack{j = 1 \\ j \neq i}}^{M} \frac{\sin(\lambda_i + \lambda_j)\sin(\gamma + \lambda_i - \lambda_j)}{\sin(2\gamma - \lambda_i - \lambda_j)\sin(\gamma - \lambda_i + \lambda_j)} \prod_{k=1}^{N} \frac{\sin(\gamma - \lambda_i + u_k)\sin(\gamma - \lambda_i - u_k)}{\sin(\lambda_i - u_k)\sin(\lambda_i + u_k)},$$

$$\text{for } i = 1, \cdots, M$$

(4.16)

and the eigenvalue $\Lambda_a^b(u, \vec{u}; \vec{\lambda})$ of the transfer matrix is given by

$$\begin{aligned}
\Lambda_a^b(u, \vec{u}; \vec{\lambda}) &= \mathcal{R}(\gamma - u)\mathcal{R}_N(u)U_{b-1}(\gamma - u)D_{a+1}(u) \\
&\times \left(\frac{\sin(2\gamma - 2u)\sin(\xi_b - u)\sin(\xi_b + b\gamma + u)}{\sin(\gamma - 2u)\sin(\xi_b - \gamma + u)\sin(\xi_b + (b+1)\gamma - u)} \right. \\
&\times \prod_{i=1}^{M} \frac{\sin(u + \lambda_i)\sin(\gamma + u - \lambda_i)}{\sin(\lambda_i - u)\sin(\gamma - u - \lambda_i)} \prod_{k=1}^{N} \sin(\gamma - u + u_k)\sin(\gamma - u - u_k) \\
&- \frac{\sin(2u)\sin(\xi_a + \gamma - u)\sin(\xi_a + (a-1)\gamma + u)}{\sin(\gamma - 2u)\sin(\xi_a + u)\sin(\xi_a + a\gamma - u)} \\
&\times \left. \prod_{i=1}^{M} \frac{\sin(u + \lambda_i - 2\gamma)\sin(\gamma - u + \lambda_i)}{\sin(u - \lambda_i)\sin(\gamma - u - \lambda_i)} \prod_{k=1}^{N} \sin(u - u_k)\sin(u + u_k) \right)
\end{aligned}$$

(4.17)

In the above analysis, ξ_a and ξ_b are respectively the free parameters associated with the boundary R-matrices at the bottom and top boundaries. They need not be related at all, hence more generally one should write them as ξ_a^- and ξ_b^+ to distinguish their origins.

5 Discussion and open problems

In this paper, we present the general trigonometric RSOS/SOS solution to the BYBE. By comparing them with the corresponding solution in the vertex representation, one may be able to obtain useful information about the vertex-SOS transformation matrix for the BYBE [20]. Indeed, for the diagonal solution, in the limit $\xi_a \to \pm i\infty$, U_{a-1} and D_{a+1} are equal so they contribute as an overall factor for the transfer matrix, since each bulk weight S_{db}^{ac} is invariant under the action of the quantum group $U_q sl(2)$ symmetry ($q = e^{i\gamma}$), the transfer matrix possesses the quantum symmetry. In this limit, the vertex-SOS transformation [25] is well known and has a precise meaning in terms

of the Clebsch-Gordan coefficients of $U_qsl(2)$. Thus for generic ξ_a, the vertex-SOS transformation can be considered as an extension of that of the $U_qsl(2)$ case.

The SOS/RSOS solutions indicate that the diagonal solution is not a special case of non-diagonal solution, in particular, there is no way of adjusting the free parameters to make all the off-diagonal scattering weights X_{bc}^a vanish. The diagonal solution is the most favorable case to be studied as we have demonstrated how the transfer matrix of the SOS lattice built up from this solution may be diagonalized. On the other hand, it is not obvious how such method can be applied to the RSOS case. In the limit π/γ becomes a rational number, solutions to the Bethe ansatz equation for the SOS model should contain those for the RSOS. However, except at the special point where there is a $U_qsl(2)$ symmetry [26], it is not clear how the RSOS solutions may be extracted. It would be an interesting challenge to extend the idea to any ξ_a. The RSOS model is indeed a very interesting case to consider; it has been shown that for a different geometry where bulk faces are oriented at an angle 45° with respective to the boundaries, the RSOS boundary condition where all spins have height a corresponds in the continuum limit to the boundary conformal state $|\tilde{h}_{1,a}\rangle$ and that with all boundary spins and their neighbors have respectively heights $a, a + 1$ corresponds to $|\tilde{h}_{a,1}\rangle$ [27]. The lattice model that we considered has a different gemeotry from that in [27], however, we believe that the difference is not significant in the scaling limit. Then the former boundary condition in fact can be obtained as the $\xi_a \to \pm i\infty$ limit of the RSOS diagonal solution since the weights U_{a-1}, D_{a+1} become the same. While the latter boundary condition can be obtained with $\xi_a = u$. So for generic ξ_a, the RSOS diagonal solution is in fact a mixture of the two above-mentioned boundary conditions and it would be interesting to examine which boundary conformal state it corresponds to in the scaling limit. Similarly, the non-diagonal solution, which gives to some extent a free boundary-like condition, may correspond to boundary conformal state $|\tilde{h}_{r,s}\rangle$ with $r, s \neq 1$ [28] in the scaling limit.

As a scattering theory, our results should be related to the conformal boundary conditions of the boundary minimal CFT and perturbations by relevant operators in the bulk and on the boundary. The non-diagonal solution, which has no free parameter, can be interpreted as the bulk Φ_{13} perturbation of the CFT with free boundary condition where all possible spins are allowed on the boundary. Additional integrable boundary perturbations introduce CDD-like factor in the scattering amplitudes. Each diagonal solution describes a perturbed CFT with a fixed boundary condition where the boundary $\mathbf{B}_a$ has fixed spin a. The parameter ξ_a in the solution should be related to the coupling constant of the boundary perturbing field. It is an open problem to relate our solutions to the specific conformal boundary conditions and boundary perturbations of generic minimal CFTs. The case $p = 4$ has been analyzed in [29].

One can also generalize our results to the coset CFTs $\mathrm{SU}(2)_k \otimes \mathrm{SU}(2)_l/\mathrm{SU}(2)_{k+l}$

perturbed by the least relevant operator in the bulk and by some boundary fields. The bulk-scattering matrices are given by

$$S = S_{\mathrm{RSOS}(k+2)} \otimes S_{\mathrm{RSOS}(l+2)} \ ,$$

where $S_{\mathrm{RSOS}(p)}$ is the RSOS S-matrix of the kinks. In this theory, particles carry two sets of RSOS spins and can be represented as $|K_{ab}\rangle \otimes |K_{a'b'}\rangle$ [12]. For the BYBE eqn.(2.1.8) with the above bulk scattering matrix, the boundary R-matrix given by

$$R = R_{\mathrm{RSOS}(k+2)} \otimes R_{\mathrm{RSOS}(l+2)} \ ,$$

is a solution, where $R_{\mathrm{RSOS}(p)}$ is the R-matrix given in eqn.(2.1.9). In particular, with $k = 2$, this is the $N = 1$ super CFTs with boundary perturbed by the least relevant operator and the R-matrix is given by that of the tri-critical Ising model tensored with that of the RSOS.

To answer some of the questions raised, finding the Bethe ansatz equation and diagonalizing the transfer matrix for the RSOS case are the essential first step. It is quite likely that one needs an alternative method such as functional approach for this purpose.

Acknowledgment

Note added in proof

After completing this work, we learned that some of the results presented in section 2, 3 have also been independently obtained in [10, 24] as their trigonometric limit.

Appendix

We present here the complete set of algebraic relations satisfied by the operators $\mathbf{X}_{bc}^a(u)$, $\mathbf{U}_a(u)$, $\mathbf{D}_a(u)$. These relations are obtained from the BYBE using eqn.(4.1) for the boundary scattering matrix. Expanding the BYBE equation and considering the various allowed heights, we get

$$
\begin{aligned}
&c_{1a}(u_+)c_{1a}(u_-)\mathbf{U}_{a-1}\mathbf{U}'_{a-1} + c_{1a}(u_-)\mathbf{X}_{a-2,a}^{a-1}\mathbf{X}_{a,a-2}^{'a-1} + c_{3a}(u',u)\mathbf{U}_{a-1}\mathbf{D}'_{a+1} \\
&= c_{1a}(u_+)c_{1a}(u_-)\mathbf{U}'_{a-1}\mathbf{U}_{a-1} + c_{1a}(u_-)\mathbf{X}_{a-2,a}^{'a-1}\mathbf{X}_{a,a-2}^{a-1} + c_{3a}(u',u)\mathbf{D}'_{a+1}\mathbf{U}_{a-1}
\end{aligned}
\tag{5.1}
$$

$$c_{2a}(u_+)c_{2a}(u_-)\mathbf{D}_{a+1}\mathbf{D}'_{a+1} + c_{2a}(u_-)\mathbf{X}^{a+1}_{a+2,a}\mathbf{X}'^{a+1}_{a,a+2} + c_{3a}(u',u)\mathbf{D}_{a+1}\mathbf{U}'_{a-1}$$
$$= c_{2a}(u_+)c_{2a}(u_-)\mathbf{D}'_{a+1}\mathbf{D}_{a+1} + c_{2a}(u_-)\mathbf{X}'^{a+1}_{a,a+2}\mathbf{X}^{a+1}_{a+2,a} + c_{3a}(u',u)\mathbf{U}'_{a-1}\mathbf{D}_{a+1} \tag{5.2}$$

$$c_{1a}f_-(u_+)\mathbf{U}_{a-1}\mathbf{U}'_{a-1} + c_{2a}f_+(u_-)\mathbf{U}_{a-1}\mathbf{D}'_{a+1} + f_-\mathbf{X}^{a-1}_{a,a-2}\mathbf{X}'^{a-1}_{a-2,a}$$
$$= c_{2a}f_-(u_+)\mathbf{D}'_{a+1}\mathbf{D}_{a+1} + c_{1a}f_+(u_-)\mathbf{U}'_{a-1}\mathbf{D}_{a+1} + f_-\mathbf{X}'^{a+1}_{a,a+2}\mathbf{X}^{a+1}_{a+2,a} \tag{5.3}$$

$$c_{2a}f_-(u_+)\mathbf{D}_{a+1}\mathbf{D}'_{a+1} + c_{1a}f_+(u_-)\mathbf{D}_{a+1}\mathbf{U}'_{a-1} + f_-\mathbf{X}^{a+1}_{a,a+2}\mathbf{X}'^{a+1}_{a+2,a}$$
$$= c_{1a}f_-(u_+)\mathbf{U}'_{a-1}\mathbf{U}_{a-1} + c_{2a}f_+(u_-)\mathbf{D}'_{a+1}\mathbf{U}_{a+1} + f_-\mathbf{X}'^{a-1}_{a,a-2}\mathbf{X}^{a-1}_{a-2,a} \tag{5.4}$$

$$c_{2a-2}(u_+)\mathbf{X}^{a-1}_{a,a-2}\mathbf{X}'^{a-1}_{a-2,a} + \mathbf{U}_{a-1}\mathbf{U}'_{a-1} = c_{2a-2}(u_+)\mathbf{X}'^{a-1}_{a,a-2}\mathbf{X}^{a-1}_{a-2,a}$$
$$+ \mathbf{U}_{a-1}\mathbf{U}'_{a-1} \tag{5.5}$$

$$c_{1a+2}(u_+)\mathbf{X}^{a+1}_{a,a+2}\mathbf{X}'^{a+1}_{a+2,a} + \mathbf{D}_{a+1}\mathbf{D}'_{a+1} = c_{1a+2}(u_+)\mathbf{X}'^{a+1}_{a,a+2}\mathbf{X}^{a+1}_{a+2,a}$$
$$+ \mathbf{D}'_{a+1}\mathbf{D}_{a+1} \tag{5.6}$$

$$\mathbf{X}^a_{a-1,a+1}\mathbf{X}'^{a+2}_{a+1,a+3} = \mathbf{X}'^a_{a-1,a+1}\mathbf{X}^{a+2}_{a+1,a+3} \tag{5.7}$$

$$\mathbf{X}^{a-1}_{a,a-2}\mathbf{D}'_{a-1} + c_{1a}(u_+)\mathbf{U}_{a-1}\mathbf{X}'^{a-1}_{a,a-2} = c_{1a}(u_-)\mathbf{X}'^{a-1}_{a,a-2}\mathbf{D}_{a-1}$$
$$+ c_{1a}(u_+)c_{1a}(u_-)\mathbf{U}'_{a-1}\mathbf{X}^{a-1}_{a,a-2} + c_{3a}(u',u)\mathbf{D}'_{a+1}\mathbf{X}^{a-1}_{a,a-2} \tag{5.8}$$

$$\mathbf{X}^{a+1}_{a,a+2}\mathbf{U}'_{a+1} + c_{2a}(u_+)\mathbf{D}_{a+1}\mathbf{X}'^{a+1}_{a,a+2} = c_{2a}(u_-)\mathbf{X}'^{a+1}_{a,a+2}\mathbf{U}_{a+1}$$
$$+ c_{2a}(u_+)c_{2a}(u_-)\mathbf{D}'_{a+1}\mathbf{X}^{a+1}_{a,a+2} + c_{3a}(u',u)\mathbf{U}'_{a-1}\mathbf{X}^{a+1}_{a,a+2} \tag{5.9}$$

$$c_{2a}(u_-)\mathbf{U}_{a+1}\mathbf{X}'^{a+1}_{a+2,a} + c_{2a}(u_+)c_{2a}(u_-)\mathbf{X}^{a+1}_{a+2,a}\mathbf{D}'_{a+1}$$
$$+ c_{3a}(u',u)\mathbf{X}^{a+1}_{a+2,a}\mathbf{U}'_{a-1} = \mathbf{U}'_{a+1}\mathbf{X}^{a+1}_{a+2,a} + c_{2a}(u_+)\mathbf{X}'^{a+1}_{a+2,a}\mathbf{D}_{a+1} \tag{5.10}$$

$$c_{1a}(u_-)\mathbf{D}_{a-1}\mathbf{X}'^{a-1}_{a,a-2} + c_{1a}(u_+)c_{1a}(u_-)\mathbf{X}^{a-1}_{a,a-2}\mathbf{U}'_{a-1}$$
$$+ c_{3a}(u',u)\mathbf{X}^{a-1}_{a-2,a}\mathbf{D}'_{a+1} = \mathbf{D}'_{a-1}\mathbf{X}^{a-1}_{a-2,a} + c_{1a}(u_+)\mathbf{X}'^{a-1}_{a-2,a}\mathbf{U}_{a-1} \tag{5.11}$$

$$f_+\mathbf{U}_{a-1}\mathbf{X}'^{a+1}_{a,a+2} = f_-\mathbf{X}'^{a+1}_{a,a+2}\mathbf{U}_{a+1} + c_{1a}(u_-)f_+\mathbf{U}'_{a-1}\mathbf{X}^{a+1}_{a,a+2}$$
$$+ c_{2a}(u_+)f_-\mathbf{D}'_{a+1}\mathbf{X}^{a+1}_{a,a+2} \tag{5.12}$$

$$f_+\mathbf{D}_{a+1}\mathbf{X}'^{a-1}_{a,a-2} = f_-\mathbf{X}'^{a-1}_{a,a-2}\mathbf{D}_{a-1} + c_{2a}(u_-)f_+\mathbf{D}'_{a+1}\mathbf{X}^{a-1}_{a,a-2}$$
$$+ c_{1a}(u_+)f_-\mathbf{U}'_{a-1}\mathbf{X}^{a-1}_{a,a-2} \tag{5.13}$$

$$f_-\mathbf{U}_{a+1}\mathbf{X}'^{a+1}_{a+2,a} + c_{1a}(u_-)f_+\mathbf{X}^{a+1}_{a+2,a}\mathbf{U}'_{a-1} + c_{2a}(u_+)f_-\mathbf{X}^{a+1}_{a+2,a}\mathbf{D}'_{a+1}$$
$$= f_+\mathbf{X}'^{a+1}_{a+2,a}\mathbf{U}_{a-1} \tag{5.14}$$

$$f_-\mathbf{D}_{a-1}\mathbf{X}'^{a-1}_{a-2,a} + c_{2a}(u_-)f_+\mathbf{X}^{a-1}_{a-2,a}\mathbf{D}'_{a+1} + c_{1a}(u_+)f_-\mathbf{X}^{a-1}_{a-2,a}\mathbf{U}'_{a-1}$$
$$= f_+\mathbf{X}'^{a-1}_{a-2,a}\mathbf{D}_{a+1} \tag{5.15}$$

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where

$$c_{1a}(u) \quad \equiv \quad \frac{\sin\gamma \sin(a\gamma - u)}{\sin(a\gamma)\sin(\gamma - u)}$$

$$c_{2a}(u) \quad \equiv \quad \frac{\sin\gamma \sin(a\gamma + u)}{\sin(a\gamma)\sin(\gamma - u)}$$

$$c_{3a}(u', u) \quad \equiv \quad \frac{\sin((a-1)\gamma)\sin((a+1)\gamma)\sin(u'+u)\sin(u'-u)}{\sin^2(a\gamma)\sin(\gamma - u' - u)\sin(\gamma - u' + u)}$$

$$f_\pm \quad \equiv \quad \frac{\sin(u' \pm u)}{\sin(\gamma - u' \mp u)}$$

$$u_\pm \quad \equiv \quad u' \pm u \,.$$

Here again, we abbreviate

$$\mathbf{U}_a \quad \equiv \quad \mathbf{U}_a(u)$$
$$\mathbf{U}'_a \quad \equiv \quad \mathbf{U}_a(u')$$

and similarly for $\mathbf{D}_a$, $\mathbf{X}^a_{bc}$.

Among them eqns.(5.9),(5.15) are of interest to us, with the help of the latter the former can be turned into the first equation in eqn.(4.6) which is more convenient for the algebraic Bethe ansatz computation.

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